# Mechanical and Electrical Vibrations 

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This illustrates a fundamental relationship between mathematics and physics: many physical problems may have the same mathematical model.

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(3) Damping: The damping or resistive force $F_{d}$ always acts in the direction opposite to the direction of motion of the mass. $F_{d}=-\gamma u^{\prime}(t)$. This force may arise from several sources: resistance from the air or other medium in which the mass moves, internal energy dissipation due to the extension or compression of the spring, friction between the mass and the guides (if any) etc.
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(9) External forces: An applied external force $F(t)$. This could be a force due to the motion of the mount to which the spring is attached, or it could be a force applied directly to the mass. Often the external force. is periodic.

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The complete formulation of the vibration problem requires that we specify two initial conditions, namely, the initial position $u_{0}$ and the initial velocity $v_{0}$ of the mass:

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u(0)=u_{0}, \quad u^{\prime}(0)=v_{0}
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spring constant: $k=\frac{m g}{L}$.

## Example 1

A mass weighing 4 lb stretches a spring 2 in . Suppose that the mass is given an additional 6 in displacement in the positive direction and then released. The mass is in a medium that exerts a viscous resistance of 6 lb when the mass has a velocity of $3 \mathrm{ft} / \mathrm{s}$. Under the assumptions discussed in this section, formulate the initial value problem that governs the motion of the mass.

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$u(0)=6 / 12, \quad u^{\prime}(0)=0 \quad$ (released with no velocity)

