

Show all work and provide brief explanations where necessary.

1. Let V be the set $\mathbb{R}^3$ and define the operations of addition and scalar multiplication by $(x, y, z) \oplus (x', y', z') = (x + x', y + y', z + z')$ and $c \odot (x, y, z) = (cx, cy, z)$ respectively. Show that with these operations, V is not a vector space.

Property (f) fails.

$$(f) \text{ says } (c+d) \odot u = (c \odot u) \oplus (d \odot u)$$

$$\begin{aligned} \text{LHS: } (c+d) \odot u &= (c+d) \odot (x, y, z) \\ &= ((c+d)x, (c+d)y, z). \end{aligned}$$

$$\begin{aligned} \text{RHS: } (c \odot u) \oplus (d \odot u) &= (c \odot (x, y, z)) \oplus (d \odot (x, y, z)) \\ &= (cx, cy, z) \oplus (dx, dy, z) \\ &= (cx+dx, cy+dy, z) \end{aligned}$$

$$\begin{aligned} \text{Now } ((c+d)x, (c+d)y, z) &\neq (cx+dx, cy+dy, z) \\ &\text{if } z \neq 0. \end{aligned}$$

2. Which of the following subsets of P_2 are subspaces? Justify your answers.

a) $S = \{at^2 + bt + c \mid a + b + c \geq 0\}$

Not a subspace

(B) fails if the scalar is negative

$$\text{let } u = t^2 \in S$$

$$r = -3$$

$$r \odot u = -3t^2 \notin S$$

S is not closed under $\odot$

b) $T = \{at^2 + bt + c \mid a + b + c = 0\}$ T is a subspace of P_2

$$\text{let } v_1 = a_1 t^2 + b_1 t + c_1 \text{ with } a_1 + b_1 + c_1 = 0$$

$$\text{and } v_2 = a_2 t^2 + b_2 t + c_2 \text{ with } a_2 + b_2 + c_2 = 0$$

$$\text{then } v_1 + v_2 = (a_1 + a_2)t^2 + (b_1 + b_2)t + (c_1 + c_2)$$

$$\text{and } (a_1 + a_2) + (b_1 + b_2) + (c_1 + c_2) = (a_1 + b_1 + c_1) + (a_2 + b_2 + c_2)$$

$$= 0 + 0 = 0, \text{ so } v_1 + v_2 \in T$$

T is closed under $\oplus$

(B) $r \in \mathbb{R}, v \in T$
 $r \odot v = r \odot (at^2 + bt + c) = rat^2 + rbt + rc$
and $ra + rb + rc = r(a + b + c) = r \cdot 0 = 0$
 T is closed under $\odot$

3. Is the set $\left\{ \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 1 & 1 \end{bmatrix} \right\}$ linearly independent in M_{22} ? Justify your answer.

$$\text{Suppose } c_1 \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + c_2 \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix} + c_3 \begin{bmatrix} 0 & 1 \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

$$\begin{aligned} \text{then } c_1 + c_2 &= 0 \\ c_2 + c_3 &= 0 \\ c_2 + c_3 &= 0 \\ c_1 + c_3 &= 0 \end{aligned} \quad \Rightarrow \quad \left[\begin{array}{ccc|c} 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 1 & 1 & 0 \\ 1 & 0 & 1 & 0 \end{array} \right]$$

$$\begin{aligned} R_4 - R_1 &\rightarrow \left[\begin{array}{ccc|c} 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & -1 & 1 & 0 \end{array} \right] \\ R_3 - R_2 &\rightarrow \left[\begin{array}{ccc|c} 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 2 & 0 \end{array} \right] \\ R_4 + R_2 &\rightarrow \left[\begin{array}{ccc|c} 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 2 & 0 \end{array} \right] \end{aligned}$$

$$\begin{aligned} \frac{1}{2} R_4 &\rightarrow \left[\begin{array}{ccc|c} 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{array} \right] \\ R_3 \leftrightarrow R_4 &\rightarrow \left[\begin{array}{ccc|c} 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right] \end{aligned}$$

$$\begin{aligned} \text{so } c_3 &= 0 \text{ (from row 3)} \\ c_2 + c_3 &= 0 \Rightarrow c_2 = 0 \text{ (row 2)} \\ c_1 + c_2 &= 0 \Rightarrow c_1 = 0 \text{ (row 1)} \end{aligned}$$

Since the only solution is the trivial solution,

$$c_1 = 0, c_2 = 0, c_3 = 0,$$

the vectors are linearly independent.

4. Determine whether or not each of the following sets of vectors is a basis of $\mathbb{R}^3$. Justify your answers.

a) $\{(1, 0, 1), (0, 1, 1)\}$

$\dim(\mathbb{R}^3) = 3$ so a basis has 3 vectors.

This set only has 2 vectors, so it is not a basis.

b) $\{(1, 0, 1), (0, 1, 1), (1, 1, 1), (0, 0, 1)\}$

This set has 4 vectors and $4 \neq 3$,
so this set is not a basis.

c) $\{(1, 0, 1), (0, 1, 1), (1, 1, 1)\}$ ← 3 vectors. Are they lin. indep?

$$c_1(1, 0, 1) + c_2(0, 1, 1) + c_3(1, 1, 1) = (0, 0, 0)$$

$$\Rightarrow c_1 + c_3 = 0, \quad c_2 + c_3 = 0, \quad c_1 + c_2 + c_3 = 0$$

$$\left(\begin{array}{ccc|c} 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 0 \\ 1 & 1 & 1 & 0 \end{array} \right) \xrightarrow{R_3 - R_1} \left(\begin{array}{ccc|c} 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 1 & 0 & 0 \end{array} \right)$$

$$\xrightarrow{R_3 - R_2} \left(\begin{array}{ccc|c} 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & -1 & 0 \end{array} \right) \Rightarrow c_3 = 0, c_2 = 0, c_1 = 0.$$

$\Rightarrow$ lin. indep. $\Rightarrow$ basis

5. Find a basis for the null space of the matrix $A = \begin{bmatrix} 1 & 3 & 0 & 1 \\ 0 & 1 & 2 & 3 \\ 1 & 5 & 4 & 7 \end{bmatrix}$.

$$R_3 - R_1 \rightarrow \begin{bmatrix} 1 & 3 & 0 & 1 \\ 0 & 1 & 2 & 3 \\ 0 & 2 & 4 & 6 \end{bmatrix} \xrightarrow{R_3 - 2R_2} \begin{bmatrix} 1 & 3 & 0 & 1 \\ 0 & 1 & 2 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$R_1 - 3R_2 \rightarrow \begin{bmatrix} 1 & 0 & -6 & -8 \\ 0 & 1 & 2 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

The system $A\vec{x} = 0$ with $\vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}$

$$\text{leads to } \left[\begin{array}{cccc|c} 1 & 0 & -6 & -8 & 0 \\ 0 & 1 & 2 & 3 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right]$$

x_3 and x_4 are free variables, so $x_3 = s$, $x_4 = t$.

and $x_1 = 6s + 8t$, $x_2 = -2s - 3t$.

$$\text{Thus } \vec{x} = \begin{bmatrix} 6s + 8t \\ -2s - 3t \\ s \\ t \end{bmatrix} = \begin{bmatrix} 6s \\ -2s \\ s \\ 0 \end{bmatrix} + \begin{bmatrix} 8t \\ -3t \\ 0 \\ t \end{bmatrix}$$

$$= s \begin{bmatrix} 6 \\ -2 \\ 1 \\ 0 \end{bmatrix} + t \begin{bmatrix} 8 \\ -3 \\ 0 \\ 1 \end{bmatrix}$$

$$\text{Null}(A) = \text{span} \left\{ \begin{bmatrix} 6 \\ -2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 8 \\ -3 \\ 0 \\ 1 \end{bmatrix} \right\}$$

Basis

6. Find bases for the column space and the row space of the matrix $A = \begin{bmatrix} 1 & 3 & 2 & 5 \\ 1 & 3 & 3 & 6 \\ 1 & 3 & 1 & 4 \\ 0 & 0 & 2 & 2 \end{bmatrix}$.

$$\begin{array}{l} R_2 - R_1 \\ R_3 - R_1 \end{array} \rightarrow \begin{bmatrix} 1 & 3 & 2 & 5 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & -1 & -1 \\ 0 & 0 & 2 & 2 \end{bmatrix} \xrightarrow{\begin{array}{l} R_3 + R_2 \\ R_4 - 2R_2 \end{array}} \begin{bmatrix} 1 & 3 & 2 & 5 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$R_1 - 2R_2 \rightarrow \begin{bmatrix} 1 & 3 & 0 & 3 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\text{Row}(A) = \text{span} \left\{ (1, 3, 0, 3), (0, 0, 1, 1) \right\}$$

basis

$$\text{Col}(A) = \text{span} \{ \text{col}_1, \text{col}_3 \text{ of } A \}$$

$$= \text{span} \left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 3 \\ 1 \\ 2 \end{bmatrix} \right\}$$

basis.

7. Use the Gram-Schmidt Process to find an orthonormal basis of the subspace W of $\mathbb{R}^4$ given by $W = \text{span}\{(1, 0, 1, 0), (1, 0, 1, 1), (0, 1, 1, 1)\}$.

$$W_1 \quad W_2 \quad W_3$$

$$\text{let } v_1 = W_1 = \boxed{(1, 0, 1, 0) = v_1}$$

$$\text{let } v_2 = W_2 - \text{proj}_{v_1}(W_2) = W_2 - \left(\frac{v_1 \cdot W_2}{v_1 \cdot v_1} \right) v_1$$

$$= (1, 0, 1, 1) - \left(\frac{2}{2} \right) (1, 0, 1, 0) = \boxed{(0, 0, 0, 1) = v_2}$$

$$\text{let } v_3 = W_3 - \text{proj}_{v_1}(W_3) - \text{proj}_{v_2}(W_3)$$

$$= W_3 - \left(\frac{v_1 \cdot W_3}{v_1 \cdot v_1} \right) v_1 - \left(\frac{v_2 \cdot W_3}{v_2 \cdot v_2} \right) v_2$$

$$= (0, 1, 1, 1) - \frac{1}{2} (1, 0, 1, 0) - \frac{1}{1} (0, 0, 0, 1)$$

$$= \left(-\frac{1}{2}, 1, \frac{1}{2}, 0 \right) ; \quad \text{New } \boxed{v_3 = (-1, 2, 1, 0)}$$

Normalize:

$$u_1 = \left(\frac{1}{\sqrt{2}}, 0, \frac{1}{\sqrt{2}}, 0 \right), \quad u_2 = (0, 0, 0, 1)$$

$$u_3 = \left(\frac{-1}{\sqrt{6}}, \frac{2}{\sqrt{6}}, \frac{1}{\sqrt{6}}, 0 \right)$$

O.N. basis for W : $\{u_1, u_2, u_3\}$.

8. Let v_1, v_2 and v_3 be vectors in a vector space such that $\{v_1, v_2\}$ is linearly independent. Show that if v_3 does not belong to $\text{span}\{v_1, v_2\}$, then $\{v_1, v_2, v_3\}$ is linearly independent.

Consider: $c_1 v_1 + c_2 v_2 + c_3 v_3 = 0$

Suppose $c_3 \neq 0$ then

$$v_3 = -\frac{c_1}{c_3} v_1 - \frac{c_2}{c_3} v_2$$

$$\Rightarrow v_3 \in \text{span}\{v_1, v_2\} \longrightarrow \leftarrow \text{(Contradiction)}$$

$$\therefore c_3 = 0.$$

This leaves $c_1 v_1 + c_2 v_2 + 0 v_3 = \vec{0}$

$$\Rightarrow c_1 v_1 + c_2 v_2 = \vec{0}$$

$$\Rightarrow c_1 = 0 \text{ and } c_2 = 0$$

since $\{v_1, v_2\}$ lin. indep.

thus $c_1 = 0, c_2 = 0$ and $c_3 = 0$

$$\Rightarrow \{v_1, v_2, v_3\} \text{ lin. indep.}$$